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# GLOBAL POSITIONING SYSTEM (GPS) PERFORMANCE

# **OCTOBER TO DECEMBER 2018**

# **QUARTERLY REPORT**

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#### 1 INTRODUCTION

### 1.1 Purpose of Document

This document presents the results of the GPS SPS performance assessment for the period of October 2018 to December 2018. The objectives of the performance assessment are to compare the measured performance against US DoD SPS performance specification [RD.1], covering the following parameters:

- SPS SiS Accuracy,
- SPS SiS Integrity,
- SPS SiS Continuity,
- SPS SiS Availability,
- PDOP Availability,
- SPS Position Service Availability and
- SPS Position Service Accuracy.

It also includes NANU analysis and geomagnetic activity.

The performance is analysed according to [AD.1] and [AD.2] using raw data recorded at the OSi site MLG1.

#### 1.2 Document Overview

This document is arranged in the following sections:

- **Section 1**, the current section, describes the purpose, scope and structure of the document and lists the reference documents.
- **Section 2** gives an introduction to the activity, including performance specification and assessment methodology and assumptions;
- **Section 3** contains an assessment of performance against GPS SPS performance standards;
- Section 4 provides an analysis of the NANUs;
- Section 5 contains the conclusions.

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# 1.3 References

# 1.3.1 Applicable Documents

Ref.	Document title	Document reference	Issue	Date
AD.1	Purchase order – GPS Performance Monitoring Service for 2018	PO 201800304	-	-
AD.2	Outline Proposal to Ordnance Survey Ireland (OSi) in response to Request for Quotation for the provision of GPS performance monitoring services for Irish Aviation Authority (IAA)	OSI-GMAS-PRP	1.0	06/03/14

Table 1-1: Applicable Documents

#### 1.3.2 Reference Documents

Ref.	Document title	Document reference	Issue	Date
RD.1	Global Positioning System Standard Positioning Service Performance Standard	GPS SPS	4 <sup>th</sup> Edition	Sept 2008
RD.2	Global Positioning System (GPS) Civil Monitoring Performance Specification	DOT-VNTSC-FAA-09-08	-	April 30 <sup>th</sup> 2009
RD.3	Reference Set of Parameters for RAIM Availability Simulations', EUROCAE WG-62	-	-	8-9 July 2003

Table 1-2: Reference Documents

# 1.4 Acronyms

Acronym	Organisation
AOD	Age Of Data
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
HDOP	Horizontal Dilution Of Precision
IAA	Irish Aviation Authority
IGS	International GNSS Service
NANU	Notice Advisory to Navstar Users

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Acronym	Organisation
NOTAM	Notice To Airmen
NSL	Nottingham Scientific Ltd
OSi	Ordnance Survey Ireland
PDOP	Position Dilution Of Precision
RAIM	Receiver Autonomous Integrity Monitoring
SIS	Signal In Space
SPS	Standard Positioning Service
TTA	Time To Alarm
UERE	User Equivalent Range Error
URA	User Range Accuracy
URE	User Range Error
VDOP	Vertical Dilution Of Precision

Table 1-3: Acronyms and Abbreviations

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# 2 INTRODUCTION

# 2.1 Purpose

The purpose of the performance monitoring activity is to collect and analyse data on the performance of the GPS Signal in Space (SIS) [AD.1]. For this report, the applicable requirements are defined in the Global Positioning System Standard Positioning Service Performance Standard (GPS SPS PS), approved by the US Department of Defence [RD.1].

#### 2.2 Performance Specification and Definitions

The applicable performance specifications for the Standard Positioning Service [RD. 1] are as follows:

Criteria	Specifications		
	The User Range Error (URE) for any healthy satellite for Single-Frequency C/A-Code:		
	≤7.8 m 95% Global Average URE during Normal Operations over all age of data (AODs)		
	≤6.0m 95% Global Average URE during Normal Operations at Zero AOD		
	≤12.8 m 95% Global Average URE during Normal Operations at Any AOD		
	≤30 m 99.94% Global Average URE during Normal Operations over one- year period		
SPS SIS	≤30 m 99.79% Worst Case Single Point Average URE during Normal Operations over one-year period		
Accuracy	≤388 m 95% Global Average URE during Extended Operations after 14 Days without Upload.		
	The User Range Rate Error (URRE) for Single-Frequency C/A-Code:		
	≤0.006 m/sec 95% Global Average URRE over any 3-second interval during Normal Operations at Any AOD		
	The User Range Acceleration Error (URAE) for Single-Frequency C/A-Code:		
	≤0.002 m/sec/sec 95% Global Average URAE over any 3-second interval during Normal Operations at Any AOD		
	The UTC Offset Error for Single-Frequency C/A-Code:		
	≤40 nsec 95% Global Average UTCOE during Normal Operations at Any AOD		

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Criteria	Specifications
	The SIS Integrity for Single-Frequency C/A-Code:
SPS SIS	<ul> <li>≤1x10<sup>-5</sup> Probability Over Any Hour of the SPS SIS Instantaneous URE Exceeding the NTE Tolerance Without a Timely Alert during Normal Operations</li> </ul>
Integrity	The UTCOE Integrity for Single-Frequency C/A-Code:
	<ul> <li>≤1x10<sup>-5</sup> Probability Over Any Hour of the SPS SIS Instantaneous UTCOE Exceeding the NTE Tolerance Without a Timely Alert during Normal Operations</li> </ul>
	SPS SIS Unscheduled Failure Interruption Continuity
SPS SIS Continuity	<ul> <li>≥ 0.9998 Probability Over Any Hour of Not Losing the SPS SIS Availability from a Slot Due to Unscheduled Interruption</li> </ul>
	Given that the SPS SIS is available from the slot at the start of the hour
	SPS SIS Per-Slot Availability
	• ≥ 0.957 Probability that a Slot in the Baseline 24-Slot Configuration will be Occupied by a Satellite Broadcasting a Healthy SPS SIS
	• ≥ 0.957 Probability that a Slot in the Expanded Configuration will be Occupied by a Pair of Satellites Each Broadcasting a Healthy SPS SIS
	SPS SIS Constellation Availability
SPS SIS Availability	• ≥ 0.98 Probability that at least 21 Slots out of the 24 Slots will be Occupied Either by a Satellite Broadcasting a Healthy SPS SIS in the Baseline 24-Slot Configuration or by a Pair of Satellites Each Broadcasting a Healthy SPS SIS in the Expanded Slot Configuration
	• ≥ 0.99999 Probability that at least 20 Slots out of the 24 Slots will be occupied either by a Satellite Broadcasting a Healthy SPS SIS in the Baseline 24-Slot Configuration or by a Pair of Satellites Each Broadcasting a Healthy SPS SIS in the Expanded Slot Configuration.
	• ≥ 0.95 Probability that the Constellation will have at least 24 Operational Satellites regardless of Whether Those Operational Satellites are Located in Slots or Not.
PDOP Availability	• ≥ 98% global Position Dilution of Precision (PDOP) of 6 or less
	• ≥ 88% worst site PDOP of 6 or less
SPS	• ≥ 99% Horizontal Service Availability average location
Position	• ≥ 90%Horizontal Service Availability worst-case location
Service	• ≥ 99% Vertical Service Availability average location
Availability	• ≥ 90% Vertical Service Availability worst-case location

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Criteria	Specifications	
	With 17 m horizontal and 37 m vertical (SIS only) 95% threshold over 24hours	
	• ≤ 9 meters 95% All-in-View Global Average Horizontal Error (SIS Only)	
	• ≤ 17 meters 95% All-in-View worst site Horizontal Error (SIS Only)	
Positioning	• ≤ 15 meters 95% All-in-View Global Average Vertical Error (SIS Only)	
Accuracy	• ≤ 37 meters 95% All-in-View worst site Vertical Error (SIS Only)	
	• ≤ 40 nanoseconds time transfer error 95% of time (SIS Only) for Time Transfer Domain Accuracy	

Table 2-1: SPS Criteria and Specifications

The definitions for each of the criteria and the methodology used for assessment are given below. As well as the GPS SPS [RD.1], the GPS civil monitoring performance specification [RD.2] has also been used to help define the methodology for the assessment.

#### **SPS SIS Accuracy**

The SPS SIS accuracy is described in two statistical ways; one way is as the 95th percentile (95%) SPS SIS user range error (URE) at a specified age of data (AOD), the other is as the 95% SPS SIS URE over all AODs. With either statistical expression, the SPS SIS accuracy is also known as the SPS SIS pseudorange accuracy. In this context, "pseudorange" means the full pseudorange data set (i.e., the matched combination of a corrected pseudorange measurement and a pseudorange origin, or equivalently the matched combination of a raw pseudorange measurement and the associated NAV data).

Other accuracy-related SPS SIS performance parameters include the SPS SIS pseudorange rate (velocity) accuracy defined as the 95% SPS SIS pseudorange rate error over all AODs and the SPS SIS pseudorange acceleration (rate rate) accuracy defined as the 95% SPS SIS pseudorange acceleration error over all AODs. These values are not monitored as part of this performance monitoring contract.

#### **SPS SIS Integrity**

The SPS SIS integrity is defined as the trust which can be placed in the correctness of the information provided by the SPS SIS. SPS SIS integrity includes the ability of the SPS SIS to provide timely alerts to receivers when the SPS SIS should not be used for positioning or timing. The SPS SIS should not be used when it is providing misleading signal-in-space information (MSI), where the threshold for "misleading" is a not-to-exceed (NTE) tolerance on the SIS URE. For this SPS PS, the four components of integrity are the probability of a major service failure, the time to alert, the SIS URE NTE tolerance, and the alert (either one or the other of two types of alerts).

- Probability of a Major Service Failure. The probability of a major service failure for the SPS SIS is defined to be the probability that the SPS SIS instantaneous URE exceeds the SIS URE NTE tolerance (i.e., MSI) without a timely alert being issued (i.e., unalerted MSI [UMSI]). Alerts generically include both alarms and warnings.
- Time to Alert. The time to alert (TTA) for the SPS SIS is defined to be the time from the onset of MSI until an alert (alarm or warning) indication arrives at the receiver's antenna. Real-time alert information broadcast as part of the NAV message data is

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defined to arrive at the receiver's antenna at the end of the NAV message subframe which contains that particular piece of real-time alert information.

SIS URE NTE Tolerance. The SPS SIS URE NTE tolerance for a healthy SPS SIS is
defined to be 4.42 times the upper bound on the URA value corresponding to the
URA index "N" currently broadcast by the satellite. The SIS URE NTE tolerance for a
marginal SPS SIS is not defined and there is no SIS URE NTE tolerance for an
unhealthy SPS SIS.

#### **SPS SIS Continuity**

The SPS SIS continuity for a healthy SPS SIS is the probability that the SPS SIS will continue to be healthy without unscheduled interruption over a specified time interval. Scheduled interruptions which are announced at least 48 hours in advance do not contribute to a loss of continuity. Scheduled SPS SIS interruptions are announced by way of the Control Segment issuing a "Notice Advisory to Navstar Users" (NANU). NANUs are similar to the "Notices to Airmen" (NOTAMs) issued regarding scheduled interruptions of ground-based air navigation aids. OCS internal procedures are to issue NANUs for scheduled interruptions at least 96 hours in advance.

#### **SPS SIS Availability**

The SPS SIS availability is the probability that the slots in the GPS constellation will be occupied by satellites transmitting a trackable and healthy SPS SIS. For this SPS Performance Standard, there are two components of availability as follows:

- Per-Slot Availability. The fraction of time that a slot in the GPS constellation will be occupied by a satellite that is transmitting a trackable and healthy SPS SIS.
- Constellation Availability. The fraction of time that a specified number of slots in the GPS constellation

#### **PDOP Availability**

PDOP availability is defined as the percentage of time over a specified time interval that the predicted PDOP is less than a specified value for any point within the service volume [RD.1].

#### **Position Service Availability**

Position service availability is defined as the percentage of time over a specified time interval that the position accuracy is less than a specified value for any point within the service volume [RD.1].

#### **Positioning Service Accuracy**

Position service accuracy is defined as the statistical difference between position measurements and a surveyed benchmark for any point within the service volume over a specified time interval [RD.1].

#### 2.3 Methodology

For the performance analysis in this report, raw GPS measurement data from reference stations has been analysed.

The primary source of data is the OSi network of active stations in Ireland. OSi operates a national network of GNSS receiver stations. The network consists of 25 receivers that provide 24-hour availability of dual frequency GPS and GLONASS data. For the purposes of this performance monitoring activity, OSi provides raw data for 2 of these sites to NSL for

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processing and analysis. The sites that are used are Mullingar (MLG1) and Sligo Hospital (SLGO). The locations of these sites are shown in Figure 2-1.



Figure 2-1: Location of Performance Monitoring Stations

In this report, MLG1 is used as the main site to provide performance monitoring across the whole of Irish airspace and SLGO is a back-up in case of problems with MLG1 and to allow cross-checking of performance in the case of anomaly investigations. These sites have been chosen to fulfil the following criteria:

- Centrally located within Ireland in order to ensure monitoring of complete airspace;
- Good data availability and continuity (i.e. avoid sites with historically poor data availability);
- Good measurement quality (i.e. avoid sites with known interference, multipath or sky visibility issues);
- Availability of required observation types and data.

During this period data from MLG1 was continuous and has been used for performance analysis for the whole period.

In case there are problems with the data access simultaneously from both MLG1 and SLGO, data from the EGNOS RIMS station at Cork will be used. The raw observation data is made available through the EGNOS Data Access Server (EDAS) in real-time or via an ftp archive. In addition to the raw data, NANU information is downloaded from the US Coast Guard Navigation Centre website (<a href="http://www.navcen.uscg.gov/?pageName=gpsNanuInfo">http://www.navcen.uscg.gov/?pageName=gpsNanuInfo</a>). This provides information on the NANUs for scheduled and unscheduled outages during the monitoring period.

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The methods for assessing of each of the requirements are described below.

#### **SPS SIS Accuracy**

SIS accuracy is assessed through processing and analysis of the raw measurement data. In order to compute the SIS accuracy, the measurements recorded at the GPS receiver are used to compute the instantaneous SIS errors. This is done by computing the difference between computed ranges (based on known receiver location and satellite position) and the corrected measurement, which has satellite and receiver clock biases, group delay, ionospheric and tropospheric errors removed. Once the SIS range errors for every satellite measurement on every epoch have been computed, the per-satellite statistics across the whole period, as well as daily statistics for all satellites combined, are generated.

#### **SPS SIS Integrity**

SIS accuracy is assessed through processing and analysis of the raw measurement data. The SIS integrity is assessed by comparing each instantaneous computed SIS error value with a threshold value of 4.42 x broadcast URA. The number of occasions where the instantaneous URE exceeds the threshold are counted and checked against the expected number of failures.

#### **SPS SIS Continuity**

SIS continuity is assessed through analysis of the broadcast navigation messages and the NANU archive. Firstly, the daily broadcast navigation messages are scanned in order to find the time periods for any satellites that do not have healthy navigation messages. These satellites and time periods are then matched against NANU information to see if the outages are scheduled or unscheduled.

The SIS continuity is computed for the baseline 24-slot constellation and is an average value over all slots. The total time that any satellites in the baseline constellation were unhealthy due to an unscheduled outage is divided by the total time in the analysis period and expressed as a percentage. Results are presented for the reporting period and, when available, for the previous year.

#### **SPS SIS Availability**

SIS availability is assessed through analysis of the broadcast navigation messages and the NANU archive. Firstly, the daily broadcast navigation messages are scanned in order to find the time periods for any satellites that do not have healthy navigation messages. These satellites and time periods are then matched against NANU information to see if the outages are scheduled or unscheduled.

The SIS availability is computed for the baseline 24-slot constellation as well as for the whole constellation and is an average value over all slots. At each epoch the number of healthy satellites (both in the baseline 24-slot constellation and in total) is counted. Then the following parameters are computed:

- Total time that there are less than 21 healthy satellites in the baseline constellation;
- Total time that there are less than 20 healthy satellites in the baseline constellation;
- Total time that there are less than 24 healthy satellites in the whole constellation.

These parameters are then divided by total time of the analysis and expressed as percentage values. Results are presented for the reporting period and, when available, for the previous year.

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It should be noted that in case the baseline 24-slot constellation does not meet requirements, the analysis will be expanded to include pairs of satellites in the expanded slot constellation.

# **PDOP Availability**

PDOP availability is assessed through processing and analysis of the raw measurement data. The PDOP availability is assessed by computing the PDOP for all satellites in view above 5 degrees at the GPS receiver at every epoch (1Hz rate). Each PDOP value is checked against the threshold value of 6 and any failures are counted. The numbers of failures on each day are then used to generate the daily availability value. A separate availability value for each day is computed.

#### **Position Service Availability**

Position service availability is assessed through processing and analysis of the raw measurement data. The derivation of the position service availability requirements of 17m (95% horizontal accuracy) and 37m (95% vertical accuracy) for 99% of the time are explained a bit more in section B.3.1 of the GPS SPS [RD.1]. The requirement is based on fulfilling a 1-sigma UERE of 4m, HDOP of 2.1 and VDOP of 4.4. To check this requirement, the following approach is used:

- For each day, compute daily rms SIS error for all satellites combined. This is equivalent to the 1-sigma UERE in the description above;
- On each epoch, multiply daily rms SIS error by HDOP value to compute estimated horizontal accuracy due to SIS error;
- For each epoch, multiply daily rms SIS error by VDOP value to compute estimated vertical accuracy due to SIS error;
- Compute daily availability (%) of estimated horizontal accuracy < 8.5m (1-sigma);</li>
- Compute daily availability (%) of estimated vertical accuracy < 18.5m (1-sigma).
- If daily availability of horizontal accuracy greater than the required threshold, the requirement for horizontal service accuracy is passed:
- If daily availability of vertical accuracy greater than the required threshold, the requirement for vertical service accuracy is passed.

#### **Positioning Service Accuracy**

In order to check the position service accuracy, the raw measurements recorded at the GPS receiver are used to compute a user position solution on every epoch (1Hz). The computed positions are then compared against the known position of the receiver in order to generate horizontal and vertical position errors. Statistics for 95% error value, 99.99% error value etc. are then computed separately for each day and checked against the thresholds.

#### 2.4 Assumptions

For processing the raw data and generating the results the following assumptions are made:

- Single frequency (L1) processing with C/A code;
- 5-degree elevation mask used:
- Broadcast iono model (Klobuchar) used to remove ionospheric errors;
- RTCA trop model used to remove tropospheric errors;

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 Weighted least squares RAIM algorithm used for RAIM prediction (protection level computation) and Fault Detection;

- Probability of missed detection = 0.001 and Probability of false alarm = 1x10<sup>-5</sup> for RAIM computations;
- UERE budget (non-SIS components) used in position solution and for RAIM predictions are given below [RD.4]:

Elevation, degrees	Error, metres
5	7.48
10	6.64
15	5.92
20	5.31
30	4.31
40	3.57
50	3.06
60	2.73
90	2.44

 The URA value from the broadcast navigation message is combined with the values in the table to form the total UERE for the observations.

As the actual monitoring is based on the measurements from one receiver the following points should be noted:

- Performance monitoring is local to the monitoring station with a coverage area defined by the correlation of the major error sources and the configuration of the constellation;
- The range domain errors contain the residuals of other error sources other than the SIS range errors; hence, the performance statistics generated are conservative.

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#### 3 SPS PERFORMANCE

#### 3.1 Baseline 24-Slot Constellation

The SPS SIS performance standard is largely based on the GPS baseline 24-slot constellation, which consists of 24 slots in six orbital planes with four slots per plane. It is important to identify the baseline constellation to act as reference to subsequent data processing and analysis. The following tables show the satellite PRN in each slot for the baseline constellation for the period October to December 2018.

Slot	A1	A2	A3	A4	B1	B2	B3	B4	C1	C2	C3	C4
PRN	24	31	30	7	16	25	28	12	29	27	8	17
Slot	D1	D2	D3	D4	E1	E2	E3	E4	F1	F2	F3	F4

Table 3-1: Baseline constellation in the Reporting Period

#### 3.2 SPS SIS Accuracy

In addition to the specifications in Table 2-1, the Conditions and Constraints for SPS SIS URE Accuracy specification [RD.1] are:

- For any healthy SPS SIS
- Neglecting single-frequency ionospheric delay model errors
- Including group delay time correction (TGD) errors at L1
- Including inter-signal bias (P(Y)-code to C/A-code) errors at L1

The statistics presented here are based on the same sample rate for positioning (1Hz). It should be noted that the computed range errors (in addition to SIS errors) contain residual errors local to the monitoring antenna (multipath, tropospheric and ionospheric). The URE Accuracy (95th percentile) values of each satellite for the period October to December 2018 are shown in the next figure.

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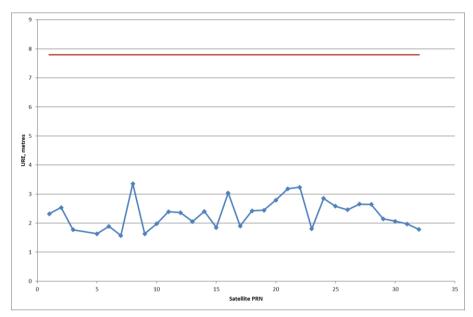


Figure 3-1: Constellation URE (95%) for Reporting Period

It can be seen that the URE (95%) for all satellites is below the 7.8m threshold. The daily constellation RMS URE results in the period October to December 2018 and the 4m threshold are shown in the next figure. Note that  $\leq$  7.8 m 95% SPS SIS URE performance standard is equivalent to a  $\leq$  4.0 m RMS SPS SIS URE performance standard [RD.1]. This is also important for the position service availability assessment.

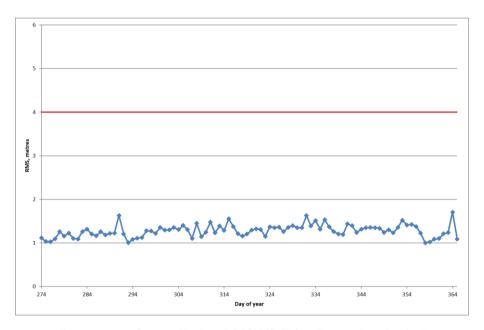


Figure 3-2: Constellation RMS URE for Reporting Period

It can be seen that the RMS values are below the threshold (4 metres) on all days. As well as the 95% and rms URE statistics, additional URE statistics are computed, including mean, 1-sigma and maximum values. Although not strictly required for the performance

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specification, these values can be useful for anomaly investigation. The range error statistics (in metres) for the period October to December 2018 are given in the table below.

PRN	Range Error (mean)	Range Error (RMS)	1-sigma	Range Error (95%)	Range Error (max)	Number of Samples
1	0.43	1.24	1.16	2.32	4.74	2320198
2	0.93	1.35	0.98	2.53	9.24	2943376
3	-0.29	0.95	0.90	1.77	6.75	2471825
5	0.27	0.81	0.77	1.63	10.75	2652296
6	-0.01	0.96	0.96	1.89	8.66	2784848
7	0.13	0.81	0.80	1.57	10.44	2863039
8	0.68	1.76	1.63	3.36	23.23	2540740
9	0.07	0.85	0.85	1.63	9.77	2586206
10	0.26	1.03	0.99	1.98	4.37	2887359
11	0.89	1.24	0.86	2.39	4.02	2066226
12	0.55	1.28	1.16	2.36	3.42	2615281
13	0.30	1.05	1.00	2.05	10.82	2306615
14	0.86	1.29	0.96	2.41	4.50	2943960
15	0.31	0.95	0.90	1.85	4.44	2471060
16	1.21	1.73	1.23	3.04	10.53	2663875
17	0.10	0.95	0.95	1.90	6.30	2915691
18	0.71	1.22	0.99	2.42	4.53	1579243
19	1.19	1.43	0.78	2.45	4.80	2863343
20	1.22	1.54	0.95	2.79	5.93	2874028
21	1.42	1.81	1.13	3.18	7.13	2884704
22	1.59	1.88	1.00	3.24	4.78	2449170
23	0.10	0.94	0.94	1.80	28.13	2734338
24	0.65	1.47	1.32	2.85	5.86	2131374
25	1.02	1.49	1.08	2.58	3.70	2388770
26	0.64	1.37	1.21	2.46	6.24	2530910
27	1.02	1.62	1.26	2.65	5.75	2407474
28	0.74	1.41	1.20	2.65	7.68	2959676
29	0.68	1.23	1.03	2.15	10.25	2744505
30	0.37	1.09	1.03	2.06	9.69	2734443
31	0.32	1.08	1.03	1.97	5.69	2791877
32	0.00	0.94	0.94	1.78	3.92	2896917

Table 3-2: Range Error Statistics for Reporting Period

Overall, the measured SIS accuracy meets the requirements during this monitoring period.

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#### 3.3 SPS SIS Integrity

In addition to the specifications in Table 2-1, the Conditions and Constraints for SPS SIS Integrity performance [RD.1] are:

- For any healthy SPS SIS;
- SPS SIS URE NTE tolerance defined to be ±4.42 times the upper bound on the URA value corresponding to the URA index "N" currently broadcast by the satellite;
- Given that the maximum SPS SIS instantaneous URE did not exceed the NTE tolerance at the start of the hour;
- Worst case for delayed alert is 6 hours;
- Neglecting single-frequency ionospheric delay model errors.

Based on the requirement of 1x10<sup>-5</sup>/hr probability for misleading information, 92-day period and a 31-satellite constellation, the maximum number of events expected is 0.67.

On every epoch throughout the monitoring period, the instantaneous measured URE for each satellite has been compared against a threshold of 4.42 times the upper value of the URA index. The number of URE values above the threshold has been recorded and is checked against the expected number.

From the analysis there are 8 days where this condition is met. On each of these days the condition lasts for 1 or 2 seconds. On further investigation it is seen that all these events affect PRN23 and always when it is between 5- and 7-degrees elevation (i.e. low down in the sky) and at around 75 degrees azimuth. In addition, it always seems to be during a period where the satellite is appearing and disappearing form the observation file, i.e. it is having trouble being tracked. Having looked also at the data from SLGO it is seen that PRN23 shows no errors at that site at the same epoch and so it appears to be a local tracking problem at MLG1 – maybe due to some local obstruction in a particular direction – that leads to larger than expected range errors. Therefore, these are not system faults and so the SIS integrity requirement is passed.

#### 3.4 SPS SIS Continuity

In addition to the specifications in Table 2-1, the Conditions and Constraints for SPS SIS Continuity performance [RD.1] are:

- Calculated as an average over all slots in the 24-slot constellation, normalized annually;
- Given that the SPS SIS is available from the slot at the start of the hour.

During this reporting period there was 17 unscheduled outages, although only 2 of them affected the baseline constellation. The total outage time of these two outages was 14.57 hrs, giving a continuity of 99.972%. Therefore, the continuity in this period does not meet the requirement of 99.98%.

#### 3.5 SPS SIS Availability

In addition to the specifications in Table 2-1, the Conditions and Constraints for SPS SIS Availability performance [RD.1] are:

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- Calculated as an average over all slots in the 24-slot constellation, normalized annually;
- Applies to satellites broadcasting a healthy SPS SIS which also satisfy the other performance standards in this SPS Performance Standard.

The total period (in this monitoring period) in which satellites from the baseline 24-satellite constellation broadcast an unhealthy SIS was 38.32 hours. This is equivalent to an average of 0.9993 over all slots in the 24-slot constellation and satisfies SPS SIS Per-slot Availability standard ( $\geq$  0.957).

The minimum number of the baseline constellation satellites broadcasting healthy SPS SIS was 23, greater than the specifications of 20 and 21. Hence, performance during the monitoring period was measured at the 100% level, satisfying the Performance Standard as specified below.

- ≥0.98 Probability that at least 21 Slots out of the 24 Slots will be Occupied Either by a Satellite Broadcasting a Healthy SPS SIS in the Baseline 24-Slot Configuration or by a Pair of Satellites Each Broadcasting a Healthy SPS SIS in the Expanded Slot Configuration;
- ≥ 0.99999 Probability that at least 20 Slots out of the 24 Slots will be occupied either by a Satellite Broadcasting a Healthy SPS SIS in the Baseline 24-Slot Configuration or by a Pair of Satellites Each Broadcasting a Healthy SPS SIS in the Expanded Slot Configuration.

The minimum number of operational satellites broadcasting healthy messages in this reporting period was 29. This represents performance at the 100% level, satisfying the Performance Standard as specified below.

• ≥ 0.95 Probability that the Constellation has at least 24 operational satellites regardless of whether the operational satellites are located in the baseline slots.

#### 3.6 PDOP Availability

In addition to the specifications in Table 2-1, the Conditions and Constraints for PDOP performance [RD.1] are:

- Defined for position solution meeting the representative user conditions and operating within the service volume over any 24-hour interval;
- Based on using only satellites transmitting standard code and indicating "healthy" in the broadcast navigation message.

The following plot shows the daily PDOP availability (PDOP < 6) calculated at the site for all healthy satellites above 5 degrees elevation during the period October to December 2018.

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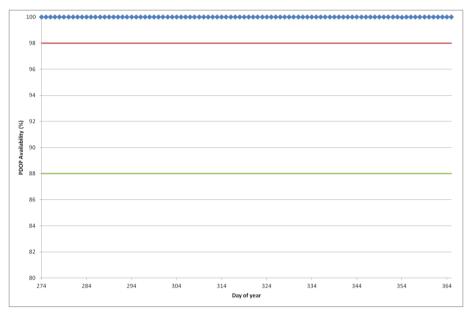


Figure 3-3: Daily PDOP Availability in the Reporting Period

It can be seen that the daily PDOP availability values are all above the thresholds of 98% (global average) and 88% (worst site). Therefore, the PDOP availability fulfils the requirements.

In addition, the daily mean and maximum PDOP values are displayed for the same period.

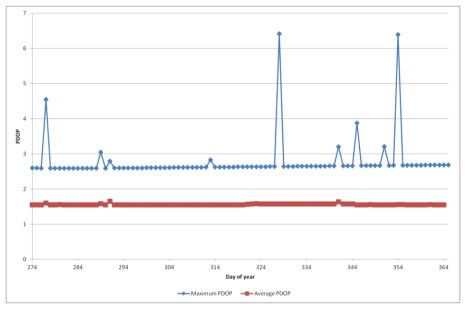


Figure 3-4: Daily Maximum PDOP Value in the Reporting Period

The daily PDOP values can be used to identify specific days that have different performance from the others. It can be seen that on most days the maximum PDOP is well below 6. There are two days where the PDOP is higher than 6, but further analysis shows that the increase in maximum PDOP on these days are caused by momentary reductions in the number of tracked satellites at MLG1, leading to a degradation in the geometry of the solution. These

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are local tracking problems at MLG1 as SLGO is not affected at these times in the same way.

#### 3.7 Position Service Availability

In addition to the specifications in Table 2-1, the Conditions and Constraints for Service Availability performance [RD.1] are:

- 17 meters horizontal (SIS only) 95% threshold;
- 37 meters vertical (SIS only) 95% threshold;
- Defined for position solution meeting representative user conditions and operating within the service volume over any 24-hour interval;
- Based on using only satellites transmitting standard code and indicating "healthy" in the broadcast navigation message.

The computation of these values is detailed in section 2.2.

The daily horizontal and vertical service availabilities for the period October to December 2018 are shown in the following figures.

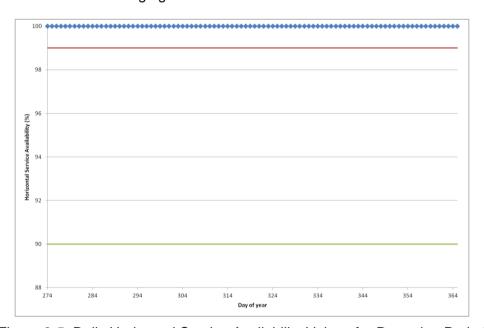


Figure 3-5: Daily Horizontal Service Availability Values for Reporting Period

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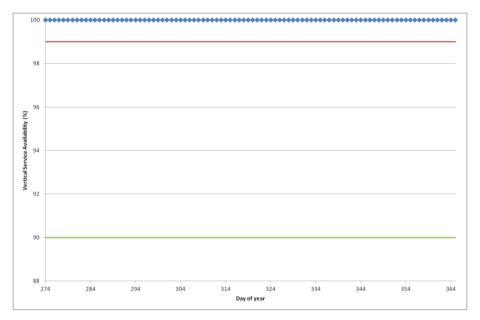


Figure 3-6: Daily Vertical Service Availability Values for Reporting Period

These plots show the horizontal and vertical availability are well above the thresholds of 99% (global average) and 90% (worst site) for the reporting period. Therefore, the position service availability fulfils the requirements.

# 3.8 Positioning Accuracy

In addition to the specifications in Table 2-1, the Conditions and Constraints for Positioning Accuracy performance [RD.1] are:

- Defined for position solution meeting the representative user conditions;
- Standard based on a measurement interval of 24 hours averaged over all points within the service volume.

For this monitoring activity it should be noted that the position accuracy is assessed through analysis of real data at a single point, rather than through service volume analysis.

The daily horizontal and vertical accuracy values (95%) for the period October to December 2018 are shown in the following figures.

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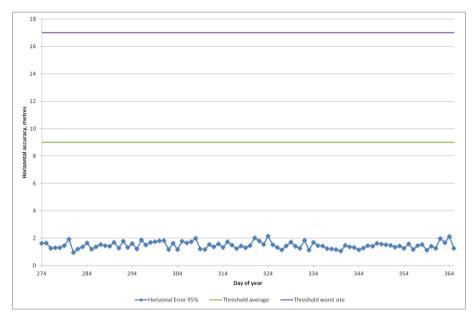


Figure 3-7: Daily Horizontal Position Accuracy (95%) for Reporting Period

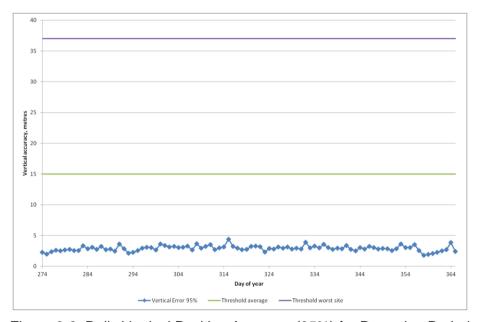


Figure 3-8: Daily Vertical Position Accuracy (95%) for Reporting Period

It can be seen that the daily horizontal accuracy values are all below the thresholds of 9m (global average) and 17m (worst site).

Also, the daily vertical accuracy values are well below the thresholds of 15m (global average) and 37m (worst site).

In addition, the daily position accuracy values at the 99.99% level are shown for the same period.

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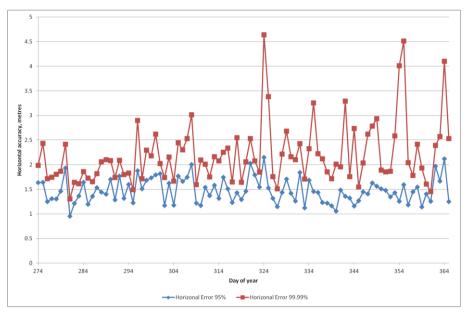


Figure 3-9: Daily Horizontal Position Accuracy (99.99%) for Reporting Period

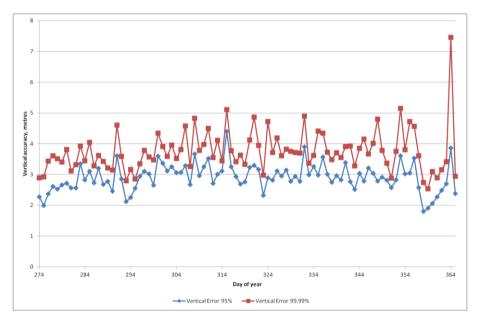


Figure 3-10: Daily Vertical Position Accuracy (99.99%) for Reporting Period

It can be seen that generally the 99.99% values generally follow the same pattern as the 95% values and are not significantly larger.

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# **4 NANU ANALYSIS**

NANU information is downloaded from the US Coast Guard Navigation Centre website (<a href="http://www.navcen.uscg.gov/?pageName=gpsNanuInfo">http://www.navcen.uscg.gov/?pageName=gpsNanuInfo</a>). Summaries of the forecast and actual outages for scheduled and unscheduled events are given below. NANUs that affect the baseline constellation are highlighted in green.

NANU	PRN	Туре	Start day	Start Time	Stop day	Stop time	Outage (hours)	Ref
2018041	9	FCSTDV	277	145	277	1345	12	F3
2018046	5	FCSTDV	289	1305	290	105	12	E3
2018054	24	FCSTDV	341	355	341	1555	12	A1
2018057	25	FCSTDV	345	535	345	1735	12	B2
2018062	25	FCSTDV	348	515	348	1715	12	B2

Table 4-1: Summary of Forecast Scheduled Outages

NANU	PRN	Туре	Start day	Start Time	Stop day	Stop time	Outage (hours)	Ref
2018043	9	FCSTSUMM	277	204	277	746	5.7	2018041
2018047	5	FCSTSUMM	289	1400	289	1930	5.5	2018046
2018058	24	FCSTSUMM	341	450	341	1114	6.4	2018054
2018064	25	FCSTSUMM	348	534	348	1143	6.15	2018062

Table 4-2: Summary of Actual Scheduled Outages

NANU	PRN	Туре	Start day	Start Time	Stop day	Stop time	Ref
2018060	25	FCSTCANC	345	535	NA	NA	2018057

Table 4-3: Summary of Cancelled Outages

NANU	PRN	Туре	Start day	Start Time	Stop day	Stop time	Outage (hours)	Ref
2018044	27	UNUSUFN	280	807	NA	NA	NA	C2
2018045	27	UNUSABLE	280	807	280	1813	10.1	2018044
2018048	18	UNUNOREF	312	1625	312	1626	0.016666	NA
2018050	18	UNUNOREF	316	1528	316	1530	0.03333	NA
2018052	18	UNUNOREF	318	1515	318	1519	0.066666	NA
2018053	18	UNUSUFN	321	1701	NA	NA	NA	D6
2018055	18	UNUSABLE	321	1701	337	1949	386.8	2018053
2018056	18	UNUSUFN	337	2309	NA	NA	NA	D6
2018059	18	UNUSABLE	337	2309	344	2027	165.3	2018056
2018061	18	UNUNOREF	345	302	345	303	0.016666	NA
2018063	18	UNUNOREF	346	352	346	358	0.1	NA
3018065	18	UNUNOREF	350	153	350	154	0.016666	NA
2018066	18	UNUNOREF	351	225	351	226	0.016666	NA
2018067	18	UNUNOREF	352	123	352	123	0.016666	NA
2018068	18	UNUNOREF	353	222	353	224	0.03333	NA

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NANU	PRN	Туре	Start day	Start Time	Stop day	Stop time	Outage (hours)	Ref
2018069	18	UNUNOREF	354	55	354	57	0.03333	NA
2018070	18	UNUNOREF	355	205	355	209	0.06666	NA
2018071	16	UNUSUFN	355	1304	NA	NA	NA	B1
2018072	16	UNUSABLE	355	1304	355	1732	4.466667	2018071
2018073	18	UNUNOREF	361	157	361	158	0.016666	NA
2018075	18	UNUNOREF	363	102	363	104	0.033333	NA

Table 4-4: Summary of Forecast and Actual Unscheduled Outages

The constellation availability and continuity figures for the baseline constellation, and for all satellites, based on the NANU information are shown in the following table.

	Q4 2018
hrs	2208
total forecast downtime (all)	60.00
total forecast downtime (baseline)	60.00
total actual scheduled downtime (all)	23.75
total actual scheduled downtime (baseline)	23.75
Scheduled satellite outage events (all)	4
Scheduled satellite outage events (baseline)	4
Unscheduled satellite outage events (all)	17
Unscheduled satellite outage events	
(baseline)	2
Total actual unscheduled downtime (all)	567.13
Total actual unscheduled downtime	
(baseline)	14.57
Total actual downtime (all)	590.88
Total actual downtime (baseline)	38.32
Availability (all)	99.137
Availability (baseline)	99.928
Continuity (baseline)	99.972

Table 4-5: Summary of NANU Statistics for Monitoring Period

From the results it can be seen that the forecast downtime was greater than the actual downtime. Also, the actual scheduled downtime periods were within the time period described in the forecast NANUs. From analysis of the broadcast navigation messages it can be seen that all occurrences of unhealthy satellites were linked with NANUs.

There were 17 unscheduled outages in this period, which is far more than usual. However, the majority were very short (2 or 3 minutes0 and affected PRN18, which is not in the baseline constellation. Nevertheless, there were two unscheduled outages that did affect the baseline constellation (on PRN27 and PRN16) and so this affects the continuity.

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# **5 CONCLUSIONS**

The following table summarises the measured performance against the specification.

Criteria	Specifications	Measured Performance	Passed
SPS SIS Accuracy	The User Range Error (URE) ≤7.8 m 95%	All SVs < 7.8m	Yes.
SPS SIS rms	≤4 m	All days <4m	Yes.
SPS SIS Integrity	The SIS Integrity ≤1x10 <sup>-5</sup> Probability Over Any Hour (<0.7 events per quarter)	No events	Yes
SPS SIS Continuity	≥ 0.9998 Probability Over Any Hour	99.97% (two unscheduled outages)	No
SPS SIS Availability	SPS SIS Per-Slot Availability  • ≥ 0.957  SPS SIS Constellation Availability  • ≥ 0.98 Probability that at least 21 Slots out of the 24 Slots will be healthy  • ≥ 0.99999 Probability that at least 20 Slots out of the 24 Slots will be healthy  • ≥ 0.95 Probability that the Constellation will have at least 24 Operational Satellites	1) 99.93% per- Slot Availability  2) 100% Constellation Availability  3) 100% probability that the number of operational satellite is larger than 24.	Yes
PDOP Availability	<ul> <li>≥ 98% global PDOP of 6 or less</li> <li>≥ 88% worst site PDOP of 6 or less</li> </ul>	>99.8% availability on all days	Yes

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Criteria	Specifications	Measured Performance	Passed
	<ul> <li>≥ 99% Horizontal Service Availability average location</li> </ul>		
SPS Position	• ≥ 90%Horizontal Service Availability worst-case location	100% availability on	
Service Availability	<ul> <li>≥ 99% Vertical Service         Availability average         location     </li> </ul>	all days	Yes
	≥ 90% Vertical Service     Availability worst-case location		
	• ≤ 9 meters 95% All-in- View Global Average Horizontal Error (SIS Only)		
Positioning	• ≤ 17 meters 95% All-in- View worst site Horizontal Error (SIS Only)	1) <3 metres 95% Horizontal Error at the site,	
Accuracy	• ≤ 15 meters 95% All-in- View Global Average Vertical Error (SIS Only)	2) <5 metres 95% Vertical Error at the site	Yes
	• ≤ 37 meters 95% All-in- View worst site Vertical Error (SIS Only)		

Table 5-1: Summary of Performance

From the table it can be seen that the measured performance is within the required values for all requirements except the continuity, which is just below the required value due to 2 unscheduled outages.

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